

**NODE PLACEMENT OPTIMIZATION USING
EXTENDED VIRTUAL FORCE AND CUCKOO SEARCH
ALGORITHM IN WIRELESS SENSOR NETWORK**

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Abstrak

Penempatan nod adalah salah satu daripada isu asas yang mempengaruhi prestasi kawasan liputan dan sambungan penerima tanpa wayar (WSN). Dalam WSN berskala besar, nod penerima disebar secara rawak di mana beberapa nod penerima adalah berselerakan terlalu rapat dan jauh dari satu sama lain. Penempatan rawak ini menyebabkan beberapa isu seperti lubang liputan, pertindihan dan kegagalan sambungan di mana ia yang menyumbang kepada prestasi kawasan liputan dan sambungan WSN. Model penempatan nod dibina untuk mencari penempatan nod yang optimum dan mengekalkan kawasan liputan serta menjamin penyambungan di dalam penempatan rawak. Prestasi Algoritma Perlanjutan Tolakan Maya (EVFA) dan algoritma Carian Cuckoo (CS) dinilai dari segi liputan dan sambungan. EVFA menunjukkan peningkatan kawasan liputan dan sambungan adalah terjamin berbanding dengan algoritma CS. Kedua-dua algoritma ini mempunyai kelebihan tersendiri dalam meningkatkan prestasi liputan selepas pelancaran rawak awal. Pendekatan EVFA boleh menyusun semula nod penerima menggunakan daya tolakan dan tarikan selepas pelancaran rawak awal dan algoritma CS adalah lebih cekap dalam meneroka carian kawasan liputan maksimum dalam penempatan rawak. Kajian ini mencadangkan algoritma Perlanjutan Tolakan Maya dan Carian Cuckoo (EVFCS) hasil gabungan antara algoritma EVFA dan CS untuk teknik penempatan nod dalam pencarian penempatan nod yang optimum. Ia bertujuan untuk meningkatkan liputan rangkaian dan hubungan dengan minimumkan lubang liputan dan kawasan bertindih. Satu siri kajian eksperimen kepada penilaian algoritma telah dijalankan dalam persekitaran simulasi. Dalam EVFCS, algoritma ini digunakan untuk mencari nilai jarak ambangan yang terbaik dan menggunakan nilai tersebut untuk menyusun semula kedudukan terbaru nod. Hasil kajian menunjukkan bahawa 18.212m adalah nilai jarak ambang terbaik yang mampu memaksimumkan kawasan liputan. Ia juga dapat mengurangkan masalah lubang liputan dan pertindihan serta menjamin kualiti sambungan. Ini membuktikan bahawa EVFCS mengatasi pendekatan EVFA dan mencapai peningkatan yang signifikan dalam kawasan liputan dan menjamin penyambungan. Perlaksanaan algoritma EVFCS dapat memperbaiki masalah yang dihadapi selepas penempatan rawak awal.

Kata kunci : Rangkaian penerima tanpa wayar, Lubang liputan, Pertindihan kawasan, Algoritma Perlanjutan Tolakan Maya dan Carian Cuckoo (EVFCS)

Abstract

Node placement is one of the fundamental issues that affects the performance of coverage and connectivity in Wireless Sensor Network (WSN). In a large scale WSN, sensor nodes are deployed randomly where they are scattered too close or far apart from each other. This random deployment causes issues such as coverage hole, overlapping and connectivity failure that contributes to the performance of coverage and connectivity of WSN. Therefore, node placement model is developed to find the optimal node placement in order to maintain the coverage and guaranteed the connectivity in random deployment. The performance of Extended Virtual Force-Based Algorithm (EVFA) and Cuckoo Search (CS) algorithm are evaluated and EVFA shows the improvement of coverage area and exhibits a guaranteed connectivity compared to CS algorithm. Both algorithms have their own strength in improving the coverage performance. The EVFA approach can relocate the sensor nodes using a repulsive and attractive force after initial deployment and CS algorithm is more efficient in exploring the search of maximum coverage area in random deployment. This study proposed Extended Virtual Force and Cuckoo Search (EVFCS) algorithm with a combination of EVFA and CS algorithm to find an optimal node placement. A series of experimental studies on evaluation of proposed algorithm were conducted within simulated environment. In EVFCS, the algorithm searches the best value of threshold distance and relocated the new position of sensor nodes. The result suggested 18.212m is the best threshold distance that maximizes the coverage area. It also minimizes the problems of coverage hole and overlapping while guaranteeing a reasonable connectivity quality. It proved that the proposed EVFCS outperforms the EVFA approach and achieved a significant improvement in coverage area and guaranteed connectivity. The implementation of the EVFCS improved the problems of initial random deployment.

Keywords: Wireless sensor network, Node placement, Coverage hole, Overlapping area Extended Virtual Force and Cuckoo Search (EVFCS) algorithm

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List of Abbreviation

ABC	Artificial Bee Colony
ACO	Ant Colony Optimization
CCP	Coverage Connectivity Protocol
CS	Cuckoo Search
EVFA	Extended Virtual Force-Based Algorithm
EVFCS	Extended Virtual Force and Cuckoo Search
FSA	Fish Swarm Algorithm
GA	Genetic Algorithm
GP	Genetic Programming
IPO	Individual Particle Optimization
PSO	Particle Swarm Optimization
QoS	Quality of Service
ROI	Region Of Interest
VFA	Virtual Force Algorithm
VFDEA	Virtual Force Based Deployment-Enhanced Algorithm
VFIPO	Virtual Force algorithm and Individual Particle Optimization
WSN	Wireless Sensor Network

CHAPTER ONE

INTRODUCTION

1.1 Background

In recent years, Wireless Sensor Networks (WSNs) have become one of the most promising technologies in sensing application environment. The WSNs provide flexibility in sensor nodes deployment and maintenance. Furthermore, it has the ability to be deployed in highly dynamic environments hence enable the sensor networks to be potentially used in a wide range of civilian and military applications [1], including security surveillance, environmental monitoring, habitat monitoring, hazard and disaster monitoring, health field applications, under-water communication [2], home applications such as smart environments and smart agriculture system [3-5]. The basic goals of a WSN generally depend on the application and have many functions which include determining the value of parameters at given location, to detect and monitor the occurrence of events and tracking an object. A wireless sensor network consists of distributed autonomous sensor nodes to cooperatively sense and monitor a physical or environmental condition, such as temperature, sound, vibration, pressure, motion or pollutants. In an environmental network [6], sensor nodes can be used to measure the temperature under atmospheric pressure, the amount of sunlight and humidity. The sensor nodes are also used to detect a vehicle movement, estimating the speed and direction of the vehicle. In a military sensor network, sensor nodes are used for battle surveillance [1] to track the enemies as they move through the geographic area covered by the network.

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